

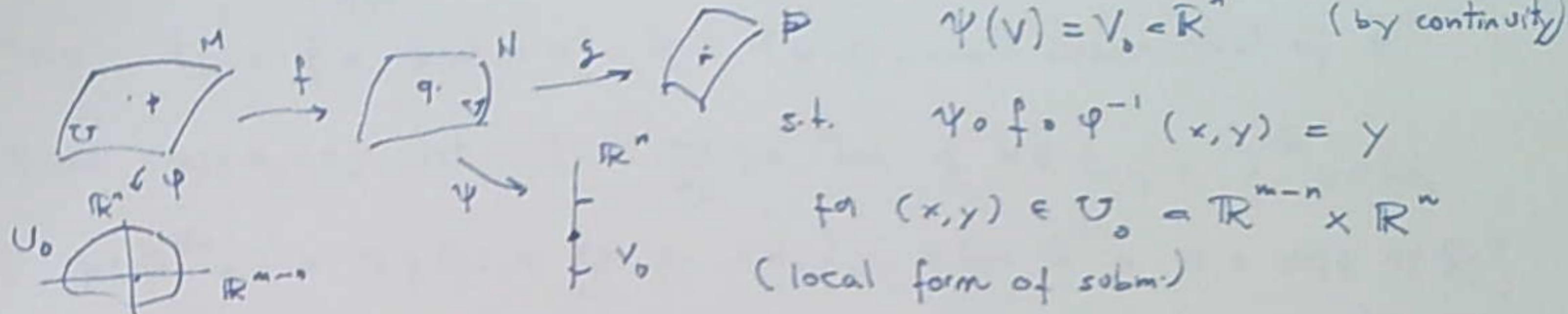
Problem set 3 - solutions

[1]

- $f: M \rightarrow N$   $C^k$  submersion (onto);  $g: N \rightarrow P$  cont.  
Assume  $g \circ f: M \rightarrow P$  is  $C^k$ . Then  $g$  is  $C^k$ .

Let  $q \in N$ ,  $p \in M$  s.t.  $f(p) = q$  (using  $f$  onto)

charts  $V$  nbd of  $q$ ,  $\psi: V \rightarrow \mathbb{R}^n$ ,  $\varphi: U \rightarrow \mathbb{R}^{m-n} = \mathbb{R}^m \times \mathbb{R}^n$ ,  $f(U) = V$



w/  $g(q) = r \in P$

on  $U$ :  
 $(g \circ f)(x) = (g \circ \psi^{-1}) \circ (\psi \circ f \circ \varphi^{-1})(\varphi(x)) \quad x \in U \quad \varphi(x) = (\varphi^1(x), \varphi^2(x)) \in \mathbb{R}^{m-n} \times \mathbb{R}^n$   
 $= (g \circ \psi^{-1})(\varphi^1(x)) \quad (g \circ \psi^{-1})(\varphi^2(x))$

or  $(g \circ f)(\varphi^{-1}(x, y)) = g(\varphi^1(y)) \quad \text{for } (x, y) \in U_0. \quad y \in V_0 \quad (\text{take } U_0 = W_0 \times V_0, \quad W_0 \subset \mathbb{R}^{m-n})$

Since  $\varphi^{-1}: U_0 \rightarrow U$  is a diff.,  $g \circ \psi^{-1}$  is  $C^k$  in  $V_0$  if  $g \circ f$

$(g \circ f)$  is  $C^k$  in  $U$ . Hence  $g$  is  $C^k$  in  $V \subset N$ .

(Note: given  $r \in P$ , we find a nbd of  $r$  (say  $W \subset P$ ), we first find a nbd  $V_1$  of  $q$  s.t.  $g(V_1) \subset W$  (using continuity), then  $V \subset V_1$  as above s.t.  $g: V \rightarrow W$  is  $C^k$ ).

- $f: M \rightarrow N$ ,  $S \subset N$  submanifold,  $f^{-1}(S)$

Then  $V = f^{-1}(S) \subset M$  is a submanifold,  $\dim_M V = \dim_N S = l$

Let  $p \in V$ ,  $q = f(p) \in S$ . Then  $\exists \begin{cases} \varphi: W \rightarrow \mathbb{R}^l, \varphi(q) = 0 \in \mathbb{R}^l \\ U \subset M \text{ nbd of } p, f(U) \subset W \end{cases}$   
 s.t.  $\varphi^{-1}(0) = S \cap W$ ,  $(\varphi \circ f): U \rightarrow \mathbb{R}^l$  is submersion and  
 $(\varphi \circ f)^{-1}(0) = U \cap V$ , with 0 a reg. value of  $\varphi \circ f$ .

so  $T_p V = \ker [d(\varphi \circ f)(p)]$ , while  $T_q S = \ker [d\varphi(q)]$

Note  $d(\varphi \circ f)(p) = d\varphi(q) \circ df(p)$  so if  $v \in T_p V$ ,  $T_q S \subset T_p V$   
 (i.e.  $df(p)^{-1}[T_q S] \subset T_p V$ )

Now conversely if  $v \in T_p V$

( $\dim T_q S = \dim N - l$ , since)

we have  $d\varphi(q) \circ df(p)[v] = 0$ , so  $df(p)[v]$  el. of  $d\varphi(q) = T_q S$ . So the subspaces coincide.

[4] We have  $\sum_{i=1}^k x^i \frac{\partial p}{\partial x^i}(x) = m p(x)$  for  $x \in \mathbb{R}^k$ .

Thus all  $a \neq 0$  in  $\mathbb{R}$  are regular values of  $p$ : if  $p(x) \neq 0$ , at least one  $\frac{\partial p}{\partial x^i}(x) \neq 0$ , so  $dp(x) \in L(\mathbb{R}^k, \mathbb{R})$  is onto.

Thus  $L_a = \{x; p(x) = a\}$  is a  $(k-1)$ -dim'l submanifold of  $\mathbb{R}^k$ .

Given  $a_1 > 0, a_2 > 0$ , let  $\lambda = \frac{a_2}{a_1} > 0$ . Then if  $x \in L_{a_1}$ ,  $\lambda^{1/m} x \in L_{a_2}$  ( $p(\lambda^{1/m} x) = \lambda p(x) = \frac{a_2}{a_1}, a_1 = a_2$ )  $x \mapsto \lambda^{1/m} x$  is a diff. of  $\mathbb{R}^k$ , which restricts to a diff.  $L_{a_1} \rightarrow L_{a_2}$ . Similar for  $a_1 < 0, a_2 < 0$

[5] (a) Consider  $\det_n: M_n \rightarrow \mathbb{R}$

We have  $\det_n(A) = \sum_{i,j} (-1)^{i+j} a_{ij} (\det_{n-1} A_{ij})$  remove  $i$ th row,  
 $j$ th column from

so  $\frac{\partial \det_n}{\partial a_{ij}}(A) = (-1)^{i+j} \det_{n-1}(A_{ij})$  and  $A$  is a crit. point

iff all  $\det_{n-1}(A_{ij})$  are zero (in which case  $\det A = 0$ )

In particular 1 is a regular value of  $\det_n$ , so  $SL(n) = \det_n^{-1}(1)$

is an  $(n^2-1)$ -dim'l submanifold of  $M_n \cong \mathbb{R}^{n^2}$ .

(b)  $T_{\mathbb{I}} SL_n = \ker [d(\det_n)(\mathbb{I})]$ . Note  $d(\mathbb{I}_{ij}) = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases}$

for  $H \in M_n$ :  $d(\det_n)(\mathbb{I})(H) = \sum_{i,j} \frac{\partial \det_n}{\partial a_{ij}}(\mathbb{I}) h_{ij} = \sum_i h_{ii} = \text{tr}(H)$

$H \in \ker [d(\det_n)(\mathbb{I})] \Leftrightarrow \text{tr } H = 0$ ,  $T_{\mathbb{I}} SL_n = \{H \in M_n; \text{tr } H = 0\}$

[6] (a)  $\Delta$  and  $W_A$  are both  $n$ -dimensional subspaces of  $\mathbb{V} \times \mathbb{V}$ .

Thus  $\Delta + W_A = \mathbb{V} \times \mathbb{V} \Leftrightarrow \Delta \cap W_A = \{0\} \Leftrightarrow (\exists w \neq 0) (Aw = w)$   
 $\Leftrightarrow 1$  is not an eigenvalue of  $A$

[6]  $\mathcal{M} = \{A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \in M_2 \setminus \{0\} \mid \det A = 0\}$  (rank 1 mod 2)

$\det(A) = ad - bc \Rightarrow d \det(A) \begin{bmatrix} x & y \\ z & w \end{bmatrix} = axw - bz - cy$

so vanishes iff for all  $(x, y, z, w) \in \mathbb{R}^4$  iff  $a = b = c = d = 0$ , i.e.  $A = 0$

thus  $\det$  is a submersion at all points of  $M_2 \setminus \{0\}$ ,

in particular  $\mathcal{M} = \det^{-1}(0) \cap (M_2 \setminus \{0\})$  is a 3-dim'l submanifold of  $M_2 \setminus \{0\}$

[3]

[7] (b) Consider the diagonal submanifold  $\Delta \subset X \times X$  (codimension  $n = \dim X$ )  
 The set of fixed points of  $f$  is the preimage of  $\Delta$  under the  
 graph embedding  $G_f: X \rightarrow X \times X$ ,  $G_f(x) = (x, f(x))$

$$\text{Fix}(f) = G_f^{-1}(\Delta).$$

Thus if  $G_f \pitchfork \Delta$ ,  $\text{Fix}(f)$  will be a submanifold of  $X$  of codimension  $n$ ,  
 i.e. dimension 0, i.e.  $\text{Fix}(f)$  consists of isolated points (finitely many, if  
 $X$  is compact).

$$\text{Now } dG_f(x)[v] = (v, df(x)[v]) \in T_x X \times T_x X$$

$$\text{if } G_f(x) \in \Delta \text{ (i.e. if } x \in \text{Fix}(f)).$$

And  $T_{(x,x)}\Delta = \Delta_{T_x X} \subset T_x X \times T_x X$ , the diagonal subspace  
 as seen in (7a),

since  $dG_f(x)[T_x X] = W_{df(x)} \subset T_x X \times T_x X$ , the ~~diagonal~~ graph  
 subspace of  $df(x) \in L(T_x X)$

$$dG_f(x)[T_x X] + \Delta_{T_x X} = T_x X \times T_x X \text{ if }$$

$$W_{df(x)} + \Delta_{T_x X} = T_x X \times T_x X$$

iff 1 is not an eigenvalue of  $T_x X$ . Thus  $G_f \pitchfork \Delta$  iff  $f$  is  
 a Lefschetz map, and then  $\text{Fix}(f)$  consists of isolated points.

[3] (a) A submersion  $f: X \rightarrow Y$  is an open map. Thus if  $X$  is  
 compact  $f(X)$  is at once compact (hence closed) and open in  $Y$ ,  
 so  $f(X) = Y$  if  $Y$  is connected.

(b) Follows from (a), since  $\mathbb{R}^n$  is connected but not compact,  
 so  $f(X) = \mathbb{R}^n$  is not possible if  $X$  is compact.