

## MORSE THEORY NOTES

### 1. Local normal form of a function at a non-degenerate critical point and the Morse Lemma.

1.1. *Linear algebra step.* Any  $B \in \text{Sym}_n$  non-degenerate (zero is not an eigenvalue) can be diagonalized by an orthogonal matrix:

$$Q^T B Q = \text{diag}(\lambda_1, \dots, \lambda_n), \quad \lambda_i \neq 0, \quad Q \in O_n.$$

Without requiring  $Q$  to be orthogonal, it is easy to see we can assume all diagonal entries are  $\pm 1$ :

$$Q^T B Q = A = \text{diag}(a_1, \dots, a_n), \quad a_i = \pm 1, \quad Q \in GL_n.$$

*Claim.* Fixing a standard form  $A = \text{diag}(a_1, \dots, a_n)$  with  $a_i = \pm 1$ , the diagonalizing matrix depends smoothly on  $B$ , for  $B \in \text{Sym}_n$  close to  $A$  in the natural topology of  $\text{Sym}_n$ . More precisely, there exists a neighborhood  $\mathcal{N}_A$  of  $A$  in  $\text{Sym}_n$  and a smooth map  $P : \mathcal{N}_A \rightarrow GL_n$  so that:

$$P(B)^T B P(B) = A, \quad \forall B \in \mathcal{N}_A, \quad P(A) = \mathbb{I}_n.$$

We present the proof in the case  $n = 2$  (for the inductive argument for all  $n$ , see [Hirsch, p.145], but beware the typo: the factor  $|b|^{-1/2}$  multiplies all entries of  $Q$ ). To avoid LaTeX coding, write  $2 \times 2$  matrices in the form  $T = [t_{11}, t_{12}, t_{21}, t_{22}]$ .

Given  $A = [a_1, 0, 0, a_2]$  with  $a_i = \pm 1$  and  $B = [b, c, c, d] \in \text{Sym}_2$  close to  $A$  (so  $b \sim a_1, c \sim 0, d \sim a_2$ ), let  $Q = |b|^{-1/2} [1, 0, -cb^{-1}, 1]$ . By direct computation, and using  $\frac{b}{|b|} = a_1$ , we find:

$$Q^T B Q = [a_1, 0, 0, d - c^2 b^{-1}].$$

Note  $d - c^2 b^{-1} \sim a_2 \neq 0$ , so define  $\alpha > 0$  by  $\alpha^2(d - c^2 b^{-1}) = a_2$ . Setting  $P = Q[1, 0, 0, \alpha] = |b|^{-1/2} [1, 0, -cb^{-1}, \alpha]$ , we find  $P^T B P = [a_1, 0, 0, a_2] = A$ . Clearly the function with values in  $GL_2$ :

$$B = [b, c, c, d] \mapsto P(B) = |b|^{-1/2} [1, 0, -cb^{-1}, |d - c^2 b^{-1}|^{-1/2}] \in GL_2$$

is smooth in a neighborhood  $\mathcal{N} \subset \text{Sym}_2$  of  $A$ , and satisfies  $P(A) = \mathbb{I}_2$ .

1.2. *Calculus step.* Let  $g : V \rightarrow \mathbb{R}$  be a smooth function, where  $V \subset \mathbb{R}^n$  is a convex neighborhood of the origin. Suppose  $g(0) = 0$  and  $dg(0) = 0$  (thus, 0 is a critical point of  $g$ .) There exists a smooth function from  $V$  to  $\text{Sym}_n$ ,  $x \mapsto B_x$ , so that:

$$g(x) = \sum_{i,j=1}^n b_{ij}(x) x_i x_j, \quad b_{ij}(0) = \partial_{x_i x_j}^2 g(0).$$

*Proof.* By the FTC, using  $g(0) = 0$  and integrating along the ray in  $V$  from the origin to  $x \in V$ :

$$g(x) = \int_0^1 \frac{dg}{dt}(tx) dt = \left( \int_0^1 \sum_{i=1}^n \partial_{x_i} g(tx) dt \right) x_i.$$

Applying the same integration argument to the partial derivatives (using the fact they all vanish at the origin):

$$(\partial_{x_i} g)(tx) = \int_0^1 \frac{dg_{x_i}}{ds}(stx) ds = \sum_j \left( \int_0^1 (\partial_{x_j x_i}^2 g)(stx) ds \right) x_j.$$

We conclude:

$$g(x) = \sum_{i,j=1}^n b_{ij}(x) x_i x_j, \quad b_{ij}(x) = \int_0^1 \int_0^1 (\partial_{x_i x_j}^2 g)(stx) ds dt.$$

*Remark:* Note that by taking  $V$  small enough, we obtain that the image  $B_x$  of this map is contained in an arbitrarily small neighborhood of the Hessian matrix of  $g$  at 0,  $H_g(0) = [\partial_{x_i x_j}^2 g(0)]$ . From the expression for  $B_x$  we have  $B_0 = H_g(0)$ .

*1.3 Normal form lemma.* Let  $g : U \rightarrow \mathbb{R}$  be a smooth function in a neighborhood of  $0 \in \mathbb{R}^n$ . Suppose  $g(0) = 0$  and 0 is a non-degenerate critical point of  $g$ . Let  $A = \text{diag}(a_1, \dots, a_n)$ ,  $a_i = \pm 1$ , be the standard diagonal form of the Hessian  $H_g(0)$ . Then there exist small neighborhoods  $V, V_1 \subset U$  of the origin and a diffeomorphism  $\varphi : V \rightarrow V_1$ ,  $y = \varphi(x)$ , so that  $g \circ \varphi^{-1}$  has the form:

$$(g \circ \varphi^{-1})(y) = \sum_i a_i y_i^2.$$

*Proof.* By (1.2), we have  $g(x) = \sum_{i,j} b_{ij}(x) x_i x_j$ , where  $B_x = (b_{ij}(x)) \in \text{Sym}_n$  is defined and smooth in a neighborhood  $V$  of 0,  $B_0 = H_g(0)$ . Taking  $V$  small enough, we find  $B_x \in \mathcal{N}$  for all  $x \in V$ , where  $\mathcal{N}$  is the neighborhood of  $A$  in  $\text{Sym}_n$  found in (1.1), on which the smooth map  $P : \mathcal{N} \rightarrow GL_n$  is defined. Let  $Q_x = P(B_x) \in GL_n$  (defined by  $Q_x^T B_x Q_x = A$ ) and define  $\varphi$  on  $V$  by:

$$\varphi(x) = Q_x^{-1}[x].$$

Then  $\varphi(0) = 0$  and the differential at 0  $D\varphi(0) = \mathbb{I}_n$ . By the inverse function theorem,  $\varphi$  is a diffeomorphism in a neighborhood of the origin (which we still denote by  $V$ ), with image equal to  $V_1$ , a second neighborhood of the origin.

Let  $y = \varphi(x)$  Then  $y = Q_x^{-1}x$ , or  $x = Q_x y$ . Thus:

$$g(x) = x^T B_x x = y^T Q_x^T B_x Q_x y = y^T A y = \sum_i a_i y_i^2,$$

or  $(g \circ \varphi^{-1})(y) = \sum_i a_i y_i^2$ .

*1.4 Morse Lemma.* If  $0 \in \mathbb{R}^n$  is a nondegenerate critical point of  $g : V \rightarrow \mathbb{R}$  of index  $k$ , we may assume the first  $k$  entries  $a_i$  in the standard form  $A$  of  $H_g(0)$  equal -1 and the last  $n - k$  equal 1. Thus there exists a decomposition  $\mathbb{R}^n = \mathbb{R}^k \oplus \mathbb{R}^{n-k}$ ,  $y = (u, v)$ , with respect to which we have:

$$g \circ \varphi^{-1}(y) = -|u|^2 + |v|^2.$$

Thus, if  $f : M \rightarrow \mathbb{R}$  is a smooth function on a smooth manifold  $M$  and  $p \in M$  is a nondegenerate critical point of  $f$ , with index  $k$ , there exists a local chart  $\psi : U \rightarrow V \subset \mathbb{R}^n$  at  $p$  so that, in this chart:

$$f \circ \psi^{-1}(y) = f(p) - |u|^2 + |v|^2, \quad y = (u, v) \in V \subset \mathbb{R}^k \oplus \mathbb{R}^{n-k}.$$

#### 4. Morse inequalities.

Let  $M$  be a compact  $n$ -dimensional manifold,  $f : M \rightarrow \mathbb{R}$  a Morse function. For  $p = 0, \dots, n$ , let:

$$\beta_p = \text{rank } H_p(M) \quad (\text{Betti numbers}), \quad \nu_p = \#\{\text{critical points of index } p\} \quad (\text{‘type numbers’}).$$

*Theorem.* We have:

$$(a) \sum_{p=0}^n (-1)^p \nu_p = \sum_{p=0}^n (-1)^p \beta_p := \chi(M) \quad (\text{euler characteristic}).$$

$$(b) \text{ for each } 0 \leq m \leq n : \sum_{p=0}^m (-1)^{m+p} \nu_p \geq \sum_{p=0}^m (-1)^{m+p} \beta_p.$$

Note that adding the statements of (b) for  $m-1$  and  $m$ , we find:

$$(c) \nu_m \geq \beta_m, 0 \leq m \leq n.$$

Statement (c) is striking: the number of critical points of a given index for *any* Morse function on  $M$  (a generic kind of function) is bounded below by the rank of homology in that dimension: topology gives a lower bound on critical points!

Also, comparing the statements (b) for  $m = n$  and  $m = n-1$  yields (a). For this reason, sometimes (a),(c) are referred to as “weak Morse inequalities”, while (b) are the “Morse inequalities”.

*Preparation for proof.* First, by perturbing  $f$  slightly (without changing the critical points  $z_i$  or their index), we may assume the  $f(z_i)$  are all distinct. For instance, let  $U_i$  be a small open neighborhood of  $z_i$ , and consider a smooth function  $\lambda_i : M \rightarrow [0, 1]$ , supported in  $U_i$  and identically 1 in a smaller neighborhood of  $z_i$ . Then, for judiciously chosen small  $\epsilon_i > 0$ , the function  $g(x) = f(x) + \sum_i \epsilon_i \lambda_i(x)$  achieves what we want.

Thus each critical value  $c_i$  has only one critical point  $z_i$  (of index  $k_i$  between 0 and  $n$ ) in its preimage. Pick the indices so the critical values  $c_i$  are an increasing sequence, then choose regular values  $a_i, i = 0, \dots, N$  separating the critical values, with  $a_0$  smaller than the minimum value  $c_0$  of  $f$  and  $a_N$  larger than the maximum value  $c_N$  (so  $f(z_0) = c_0$  with index 0 and  $f(z_N) = c_N$  of index  $n$ ):

$$a_0 < c_0 < a_1 < c_1 < \dots < a_{N-1} < c_N < a_N.$$

For  $j = 0, \dots, N$ , consider the sublevel set  $M_j = f^{-1}[a_0, a_j] = \{x \in M; f(x) \leq a_j\}$ , a manifold with boundary  $\partial M_j$  equal to the (regular) level set at  $a_j$ . Clearly  $M = M_N$  is the increasing union of the  $M_j$ , with  $M_0 = \emptyset$ . Adopt the notation:

$$\beta(p, j) = \text{rk } H_p(M_j), j = 0, \dots, n, \quad \text{so } \beta(p, 0) = 0, \beta(p, N) = \beta_p.$$

$$\alpha(p, j) = \text{rk } H_p(M_j, M_{j-1}), \quad j = 1, \dots, N.$$

In part (3) we proved that  $M_j$  differs from  $M_{j-1}$  (up to homotopy type) by attaching a cell of dimension  $k_j$ . More precisely, there exists a closed  $k_j$ -cell  $e^{k_j}$  contained in the interior of  $M_j$ , with boundary  $\partial e^{k_j} \subset M_{j-1}$ , so that  $M_{j-1} \cup e^{k_j}$  is a deformation retract of  $M_j$ . So we have inclusions:

$$A_j := (M_{j-1} \setminus \partial e^{k_j}) \subset M_{j-1} \subset M_{j-1} \cup e^{k_j}, \quad \overline{A_j} \subset M_{j-1},$$

$$(M_{j-1} \cup e^{k_j}) \setminus A_j = e^{k_j}, \quad M_{j-1} \setminus A_j = \partial e^{k_j}.$$

Thus, by the excision theorem (excising  $A_j$ ) and the fact  $M_{j-1} \cup e^{k_j}$  is a deformation retract of  $M_j$ , we have, for each  $p = 0, \dots, n$ :

$$H_p(M_j, M_{j-1}) \approx H_p(M_{j-1} \cup e^{k_j}, M_{j-1}) \approx H_p(e^{k_j}, \partial e^{k_j}),$$

which has rank equal to 1 if  $p = k_j$  and 0 otherwise.

Thus the terms in the sum  $\sum_{j=0}^N \alpha(p, j)$  (for fixed  $p$ ) are equal to 1 if  $k_j = p$  and zero otherwise. In other words, the value of the sum is the number of  $j$  for which  $k_j = p$ , that is, the number of critical points of  $f$  of index  $p$ , which we have denoted by  $\nu_p$ .

*Proof of statement (a) in the theorem.* Recall the fact (exercise 5.5 in [Rotman, p. 87]) that in any long exact sequence of finitely generated abelian groups:

$$0 \rightarrow A_n \rightarrow A_{n-1} \rightarrow \dots \rightarrow A_1 \rightarrow A_0 \rightarrow 0$$

the alternating sum of ranks vanishes:  $\sum_{j=0}^n (-1)^j \text{rk}(A_j) = 0$ . Apply this to the long exact sequence in homology of the pair  $(M_j, M_{j-1})$ , for fixed  $j = 1, \dots, N$ :

$$\begin{aligned} 0 \rightarrow H_n(M_{j-1}) \rightarrow H_n(M_j) \rightarrow H_n(M_j, M_{j-1}) \rightarrow H_{n-1}(M_{j-1}) \rightarrow \dots \\ \dots \rightarrow H_0(M_{j-1}) \rightarrow H_0(M_j) \rightarrow H_0(M_j, M_{j-1}) \rightarrow 0. \end{aligned}$$

Grouping the terms in the alternating sum of ranks by threes, we find:

$$\sum_{p=0}^n (-1)^p [\beta(p, j-1) - \beta(p, j) + \alpha(p, j)] = 0.$$

Adding this expression over  $j = 1, \dots, N$ , we find (noting the telescoping sum, and using  $\beta(p, N) = \beta_p, \beta(p, 0) = 0$ ):

$$\sum_{p=0}^n \sum_{j=1}^N (-1)^p \alpha(p, j) = \sum_{p=0}^n (-1)^p \sum_{j=1}^N [\beta(p, j) - \beta(p, j-1)] = \sum_{p=0}^n (-1)^p \beta_p,$$

and recalling that the sum on the left equals  $\sum_{p=0}^n (-1)^p \nu_p$ , this proves statement (a).

*Proof of statement (b) in the theorem.* This is similar, considering instead the long exact sequence for the pair  $(M_j, M_{j-1})$  starting at homology in dimension  $m$ :

$$\begin{aligned} 0 \rightarrow K_{m,j} \rightarrow H_m(M_{j-1}) \rightarrow H_m(M_j) \rightarrow H_m(M_j, M_{j-1}) \rightarrow H_{m-1}(M_{j-1}) \rightarrow \dots \\ \dots \rightarrow H_0(M_{j-1}) \rightarrow H_0(M_j) \rightarrow H_0(M_j, M_{j-1}) \rightarrow 0. \end{aligned}$$

Here  $K_{m,j}$  is the kernel of the inclusion homomorphism  $H_m(M_{j-1}) \rightarrow H_m(M_j)$ ; denote its dimension by  $\kappa_{m,j}$ . Again grouping the alternating sum of ranks by threes (and including the additional term), we find for fixed  $j$ :

$$\sum_{p=0}^m (-1)^p [\beta(p, j-1) - \beta(p, j) + \alpha(p, j)] + (-1)^{m+1} \kappa_{m,j} = 0,$$

or

$$0 \leq \kappa_{m,j} = \sum_{p=0}^m (-1)^{p+m} [\beta(p, j-1) - \beta(p, j) + \alpha(p, j)].$$

Adding over  $j = 1, \dots, N$  as before, we find:

$$\sum_{p=0}^m (-1)^{p+m} [\nu_p - \beta_p] \geq 0,$$

which is statement (b).

**Problems.** (Source: [Hirsch, *Differential Topology*])

1. Let  $M \subset \mathbb{R}^q$  be a compact smooth submanifold. For each  $v \in S^q$ , let  $f_v : M \rightarrow \mathbb{R}$  be the function  $f_v(x) = \langle v, x \rangle$ . Then the set of  $v \in S^q$  such that  $f_v$  is a Morse function is open and dense.

2. Define the function  $g : RP^n \rightarrow \mathbb{R}$  on real projective space by the formula:

$$f[x_0, x_1, \dots, x_n] = \frac{\sum \lambda_j |x_j|^2}{\sum |x_j|^2},$$

where the  $\lambda_j$  are distinct real numbers. Show  $f$  is a Morse function of type  $(1, 1, 1, 1, \dots, 1, 1, 1)$ . Describe the CW structure on  $RP^n$  that follows from this.

3. Let  $f : S^n \rightarrow \mathbb{R}$  be a Morse function invariant under the antipodal map  $x \mapsto -x$ . Then  $f$  has at least two critical points of each index  $0, 1, \dots, n$ . [Consider the function induced on  $RP^n$ . The  $\mathbb{Z}_2$  Betti numbers of  $RP^n$  are  $1, 1, \dots, 1$ .]

4. Let  $S$  be a compact orientable surface of genus  $p$ . (a) Every Morse function on  $S$  has at least  $2p + 2$  critical points. (b) Some Morse function on  $S$  has exactly this number of critical points.