MATRIX FACTORIZATIONS

- 1 $\mathbf{A} = \mathbf{L}\mathbf{U} = \begin{pmatrix} \text{lower triangular } L \\ \text{1's on the diagonal} \end{pmatrix} \begin{pmatrix} \text{upper triangular } U \\ \text{pivots on the diagonal} \end{pmatrix}$ Section 2.5 Requirements: No row exchanges as Gaussian elimination reduces A to U.
- 2 $A = LDU = \begin{pmatrix} lower triangular L \\ l's on the diagonal \end{pmatrix} \begin{pmatrix} pivot matrix \\ D is diagonal \end{pmatrix} \begin{pmatrix} upper triangular U \\ l's on the diagonal \end{pmatrix}$ Requirements: No row exchanges. The pivots in D are divided out to leave 1's in U. If A is symmetric then U is the transpose of L and $A = LDL^T$. Section 2.5
- 3 PA = LU (permutation matrix P to reorder the rows of A). Requirements: A is invertible. Then P, L, U are invertible. P does the row exchanges in advance. Alternative: $A = L_1 P_1 U_1$. Section 2.6
- 4 PA = LU = (m by m lower triangular matrix L)(m by n echelon matrix U).

 Requirements: None! U has r pivot rows and pivot columns, with zeros below pivots. Complete elimination gives the reduced echelon form R. Section 3.2
- 5 $A = CC^T = (\text{lower triangular matrix } C)$ (transpose is upper triangular) Requirements: A is symmetric and positive definite (all n pivots in D are positive). This Cholesky factorization has $C = L\sqrt{D}$. Section 6.5
- 6 A = QR = (orthonormal columns in Q) (upper triangular R)

 Requirements: A has independent columns. Those are orthogonalized in Q by the Gram-Schmidt process. If A is square then $Q^{-1} = Q^{T}$. Section 4.3
- 7 $A = SAS^{-1} = (eigenvectors in S)(eigenvalues in <math>\Lambda)(left eigenvectors in S^{-1}).$ Requirements: A has n linearly independent eigenvectors. Section 6.2
- 8 $A = Q\Lambda Q^T = (\text{orthogonal matrix } Q)(\text{real eigenvalue matrix } \Lambda)(Q^T \text{ is } Q^{-1}).$ Requirements: A is symmetric. This is the Spectral Theorem. Section 6.4

9 $\mathbf{A} = \mathbf{MJM}^{-1} = (\text{generalized eigenvector matrix } M)(\text{Jordan block matrix } J)(M^{-1}).$

Requirements: A is any square matrix. Number of independent eigenvectors of A is the number of blocks in the *Jordan form J*. Each block has one eigenvalue. Section 6.6

- 10 $A = U\Lambda U^{-1} = (\text{unitary } U)(\text{eigenvalue matrix } \Lambda)(U^{-1} \text{ which is } U^{\text{H}} = \overline{U}^{\text{T}}).$ Requirements: A is normal: $A^{\text{H}}A = AA^{\text{H}}$. Its orthonormal (and possibly complex) eigenvectors are the columns of U. Complex λ 's unless $A = A^{\text{H}}$. Section 10.2
- 11 $A = UTU^{-1} = (unitary \ U)(triangular \ T \ with \ \lambda$'s on diagonal) $(U^{-1} \ which \ is \ U^{H})$.

Requirements: Schur triangularization of any square A. There is a matrix U with orthonormal columns that makes $U^{-1}AU$ triangular. Section 10.2

- 12 $\mathbf{A} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^{\mathrm{T}} = \begin{pmatrix} \text{orthogonal} \\ U \text{ is } m \times m \end{pmatrix} \begin{pmatrix} m \times n \text{ singular value matrix} \\ \sigma_{1}, \dots, \sigma_{r} \text{ on its diagonal} \end{pmatrix} \begin{pmatrix} \text{orthogonal} \\ V \text{ is } n \times n \end{pmatrix}$.

 Requirements: None. This singular value decomposition (SVD) has the eigenvectors of $A^{\mathrm{T}}A$ in U and of AA^{T} in V; $\sigma_{i} = \sqrt{\lambda_{i}(A^{\mathrm{T}}A)} = \sqrt{\lambda_{i}(AA^{\mathrm{T}})}$. Section 7.3
- 13 $A^+ = V\Sigma^+U^T = \begin{pmatrix} \text{orthogonal} \\ n \times n \end{pmatrix} \begin{pmatrix} n \times m \text{ pseudoinverse of } \Sigma \\ 1/\sigma_1, \dots, 1/\sigma_r \text{ on diagonal} \end{pmatrix} \begin{pmatrix} \text{orthogonal} \\ m \times m \end{pmatrix}$.

 Requirements: None. The *pseudoinverse* has $A^+A = \text{projection onto row space}$ of A and $AA^+ = \text{projection onto column space}$. The shortest least-squares solution to $A\mathbf{x} = \mathbf{b}$ is $\bar{\mathbf{x}} = A^+\mathbf{b}$. Section 7.3
- 14 A = QH = (orthogonal matrix Q)(symmetric positive definite matrix H).Requirements: A is invertible. This polar decomposition has $H^2 = A^TA$. The factor H is semidefinite if A is singular. The reverse polar decomposition A = KQ has $K^2 = AA^T$. Both have $Q = UV^T$ from the SVD. Section 7.3
- 15 $\mathbf{F}_{\mathbf{n}} = \begin{bmatrix} I & D \\ I & -D \end{bmatrix} \begin{bmatrix} F_{n/2} & \\ & F_{n/2} \end{bmatrix} \begin{bmatrix} \text{even-odd permutation} \end{bmatrix}$

Requirements: F_n = Fourier matrix with entries w^{jk} where $w^n = 1$. Then $F_n\overline{F}_n = nI$. D has $1, w, w^2, \ldots$ on its diagonal. For $n = 2^l$ the Fast Fourier Transform has $\frac{1}{2}nl$ multiplications from l stages of D's. Section 10.3

The factorizations 1–8 are in the basic course; 9–15 are optional.