

1) [10 points] Let  $\mathbf{u} = (1, 1)$  and  $\mathbf{v} = (3, k)$ . Find  $k$  such that the angle between  $\mathbf{u}$  and  $\mathbf{v}$  is  $\pi/4$ .

*Solution.* We have:

$$(1, 1) \cdot (3, k) = \|(1, 1)\| \|(3, k)\| \cos(\pi/4).$$

So,

$$3 + k = \sqrt{2} \sqrt{9 + k^2} \sqrt{2}/2 = \sqrt{k^2 + 9}$$

Squaring:

$$k^2 + 6k + 9 = k^2 + 9,$$

and hence  $6k = 0$ , i.e.,  $k = 0$ .

Now, since we've squared the equation, we need to check that we've got it right [as squaring " $1 = -1$ " gives a true statement], but indeed,

$$\frac{(1, 1) \cdot (3, 0)}{\sqrt{2} \cdot 3} = \frac{1}{\sqrt{2}} = \frac{\sqrt{2}}{2} = \cos(\pi/4).$$

[To see why this is necessary, replace  $(3, k)$  by  $(-3, k)$ . The algebra will give you  $k = 0$ , but the fact is that there is no  $k$  that will make the angle  $\pi/4$ .]

[Note that this could be easily seen geometrically.]

□

2) [20 points] Give the matrix that represents the following linear transformation (from  $\mathbb{R}^3$  to  $\mathbb{R}^3$ ): projection to the  $xy$ -plane, followed by a rotation of  $\pi/2$  around the  $z$ -axis, followed by a reflection on the  $yz$ -plane.

*Solution.* We find the matrix by checking what it does to the standard basis vectors  $\mathbf{e}_1 = (1, 0, 0)$ ,  $\mathbf{e}_2 = (0, 1, 0)$ , and  $\mathbf{e}_3 = (0, 0, 1)$ .

$$\mathbf{e}_1 \longrightarrow \mathbf{e}_1 \longrightarrow \mathbf{e}_2 \longrightarrow \mathbf{e}_2,$$

also,

$$\mathbf{e}_2 \longrightarrow \mathbf{e}_2 \longrightarrow -\mathbf{e}_1 \longrightarrow \mathbf{e}_1,$$

and finally,

$$\mathbf{e}_3 \longrightarrow \mathbf{0} \longrightarrow \mathbf{0} \longrightarrow \mathbf{0}.$$

So, the matrix is:

$$\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$

Alternatively, the matrices for the three transformations are, respective:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \quad \begin{bmatrix} \cos(\pi/2) & -\sin(\pi/2) & 0 \\ \sin(\pi/2) & \cos(\pi/2) & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix},$$

and hence the matrix of the linear transformation we are looking for is:

$$\begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$

□

**3)** [15 points] Let  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be a linear transformation such that  $T(2, 1) = (3, 0)$  and  $T(0, 1) = (1, -2)$ . Find the inverse of  $T$  or show that such inverse does not exist.

*Solution.* We have that the first column of  $[T]$  is  $T(1, 0)$ , while the second column is  $T(0, 1)$ . Hence, the statement gives us the second column. To find the first, we have [since  $T$  is linear], we have that

$$(3, 0) = T(2, 1) = T(2(1, 0) + (0, 1)) = 2T(1, 0) + T(0, 1) = 2T(1, 0) + (1, -2).$$

Solving for  $T(1, 0)$ , we have  $T(1, 0) = 1/2(2, 2) = (1, 1)$ , and hence,

$$[T] = \begin{bmatrix} 1 & 1 \\ 1 & -2 \end{bmatrix}.$$

Then  $T$  is invertible if, and only if, the matrix  $[T]$  is invertible, which is true:

$$[T^{-1}] = [T]^{-1} = -\frac{1}{3} \begin{bmatrix} -2 & -1 \\ -1 & 1 \end{bmatrix}.$$

Thus,

$$T^{-1}(x, y) = \left( \frac{2x + y}{3}, \frac{x - y}{3} \right).$$

□

4) [15 points] Let  $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$  be a linear transformation and assume that 0 is an eigenvalue of  $T$ . Can  $T$  be one-to-one? Can it be onto? Justify your answers!

*Proof.* No [for both]. Saying that 0 is an eigenvalue is the same as to say that there is a vector  $\mathbf{v} \neq \mathbf{0}$  such that  $T(\mathbf{v}) = 0 \cdot \mathbf{v} = \mathbf{0}$ . Hence, since always for a linear transformation  $T(\mathbf{0}) = \mathbf{0}$ , we have two different vectors [namely,  $\mathbf{v}$  and  $\mathbf{0}$ ] with the same value by  $T$  [namely,  $\mathbf{0}$ ], and hence  $T$  is not one-to-one.

Now, since the domain and codomain of  $T$  are equal [namely,  $\mathbb{R}^n$ ], we have that  $T$  is one-to-one if, and only if, it is onto. Hence, since  $T$  is not one-to-one, it cannot be onto.

□

5) [15 points] Let  $V = \mathbb{R}^2$  with the usual sum of vectors in  $\mathbb{R}^2$ , but with the following multiplication by real numbers:  $k(x, y) = (ky, kx)$ . Show that  $V$  is *not* a vector space.

*Solution.* We have

$$1(1, 0) = (0, 1),$$

and thus, property 8 [from the list given below] fails. Hence, it cannot be a vector space.

[You could also show instead the property 7 fails:

$$(2 \cdot 3)(1, 0) = 6(0, 1) = (0, 6),$$

while

$$2(3(1, 0)) = 2(0, 3) = (6, 0).$$

But, you only need to show that one fails.]

□

6) [10 points] Consider the set of all matrices

$$\begin{bmatrix} a & 1 \\ 2 & b \end{bmatrix}, \quad a, b \in \mathbb{R}.$$

with:

$$\begin{bmatrix} a & 1 \\ 2 & b \end{bmatrix} + \begin{bmatrix} a' & 1 \\ 2 & b' \end{bmatrix} = \begin{bmatrix} a+a' & 1 \\ 2 & b+b' \end{bmatrix}, \quad k \begin{bmatrix} a & 1 \\ 2 & b \end{bmatrix} = \begin{bmatrix} ka & 1 \\ 2 & kb \end{bmatrix}.$$

This set with this sum and scalar multiplication *is* a vector space. [You do not need to prove it! Just take my word for it.] What is the zero of this vector space? What is

$$-\begin{bmatrix} 3 & 1 \\ 2 & -1 \end{bmatrix}?$$

*Solution.* If

$$0 = \begin{bmatrix} x & 1 \\ 2 & y \end{bmatrix},$$

we must have that

$$\begin{bmatrix} a & 1 \\ 2 & b \end{bmatrix} + \begin{bmatrix} x & 1 \\ 2 & y \end{bmatrix} = \begin{bmatrix} a+x & 1 \\ 2 & b+y \end{bmatrix} = \begin{bmatrix} a & 1 \\ 2 & b \end{bmatrix}.$$

Thus, we must have  $x = y = 0$ , i.e.,

$$0 = \begin{bmatrix} 0 & 1 \\ 2 & 0 \end{bmatrix}.$$

If

$$-\begin{bmatrix} 3 & 1 \\ 2 & -1 \end{bmatrix} = \begin{bmatrix} x & 1 \\ 2 & y \end{bmatrix},$$

we must have that

$$\begin{bmatrix} 3 & 1 \\ 2 & -1 \end{bmatrix} + \begin{bmatrix} x & 1 \\ 2 & y \end{bmatrix} = \begin{bmatrix} 3+x & 1 \\ 2 & -1+y \end{bmatrix} = 0 = \begin{bmatrix} 0 & 1 \\ 2 & 0 \end{bmatrix}.$$

Thus, we must have  $x = -3$  and  $y = 1$ , i.e.,

$$-\begin{bmatrix} 3 & 1 \\ 2 & -1 \end{bmatrix} = \begin{bmatrix} -3 & 1 \\ 2 & 1 \end{bmatrix}.$$

□

7) [15 points] Let  $V$  be the set of all functions [from  $\mathbb{R}^2$  to  $\mathbb{R}^2$ ] of the form  $f(x, y) = (ax + by, ax^2 + by^2)$ , where  $a, b \in \mathbb{R}$ . Is  $V$  a vector space with the usual sum and scalar multiplication of functions? [Justify!]

*Solution.* The set of functions from  $\mathbb{R}^2$  to  $\mathbb{R}^2$ , since  $\mathbb{R}^2$  is a vector space, is itself a vector space [which I denoted in class by  $F(\mathbb{R}^2, \mathbb{R}^2)$ ]. Since  $V$  is inside this vector space [and we are using the same operations], it suffices to show that it is a subspace.

If  $f(x, y) = (ax + by, ax^2 + by^2)$  and  $g(x, y) = (a'x + b'y, a'x^2 + b'y^2)$ , then

$$f(x, y) + g(x, y) = ((a + a')x + (b + b')y, (a + a')x^2 + (b + b')y^2),$$

and hence  $f(x, y) + g(x, y) \in V$ .

Also, given any  $k \in \mathbb{R}$ ,

$$kf(x, y) = ((ka)x + (kb)y, (ka)x^2 + (kb)y^2),$$

and hence  $kf(x, y) \in V$ .

These two properties gives us that  $V$  is then a vector space [more precisely, a subspace of  $F(\mathbb{R}^2, \mathbb{R}^2)$ ]. [Note that  $V$  is not empty, as  $f(x, y) = (0, 0) \in V$ .]

□

## Vector Space Requirements

A non-empty set  $V$  with a sum and a scalar product is a vector space if it satisfies the following conditions:

0.  $\mathbf{u} + \mathbf{v} \in V$  for all  $\mathbf{u}, \mathbf{v} \in V$ , and  $k\mathbf{u} \in V$  for all  $\mathbf{u} \in V$  and  $k \in \mathbb{R}$ ;
1.  $\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$  for all  $\mathbf{u}, \mathbf{v} \in V$ ;
2.  $(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w})$  for all  $\mathbf{u}, \mathbf{v}, \mathbf{w} \in V$ ;
3. there is  $\mathbf{0} \in V$  such that  $\mathbf{0} + \mathbf{u} = \mathbf{u}$  for all  $\mathbf{u} \in V$ ;
4. given  $\mathbf{u} \in V$ , there exists  $-\mathbf{u} \in V$  such that  $\mathbf{u} + (-\mathbf{u}) = \mathbf{0}$ ;
5.  $k(\mathbf{u} + \mathbf{v}) = k\mathbf{u} + k\mathbf{v}$  for all  $\mathbf{u}, \mathbf{v} \in V$  and  $k \in \mathbb{R}$ ;
6.  $(k + l)\mathbf{u} = k\mathbf{u} + l\mathbf{u}$  for all  $\mathbf{u} \in V$  and  $k, l \in \mathbb{R}$ ;
7.  $k(l\mathbf{u}) = (kl)\mathbf{u}$  for all  $\mathbf{u} \in V$  and  $k, l \in \mathbb{R}$ ;
8.  $1\mathbf{u} = \mathbf{u}$  for all  $\mathbf{u} \in V$ .